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16 recommended by the manufacturer after 3,850 hours of use or one calendar year — whichever is earlier. For other manufacturers, maintenance of industrial robots may be recommended up to every 10,000 hours.

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16 explores three technologies that are the building blocks of the next-generation advanced manufacturing. The first technology covered in Volume 1 is Additive Manufacturing (AM). AM has emerged as a very popular manufacturing process. The most common form of AM is referred to as 'three-dimensional (3D)

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printing'. Overall, the revolution of additive manufacturing has led to many opportunities in fabricating complex, customized, and novel products. As the number of printable materials increases and AM processes evolve, manufacturing capabilities for future engineering systems will expand rapidly, resulting in a

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16 completely new paradigm for solving a myriad of global problems. The second technology is industrial robots, which is covered in Volume 2 on Robotics.

Traditionally, industrial robots have been used on mass production lines, where the same manufacturing operation is repeated many times. Recent advances in human-

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16 safe industrial robots present an opportunity for creating hybrid work cells, where humans and robots can collaborate in close physical proximities. This Cobots, or collaborative robots, has opened up to opportunity for humans and robots to work more closely together. Recent advances in artificial intelligence are striving to make

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Industrial robots more agile, with the ability to adapt to changing environments and tasks. Additionally, recent advances in force and tactile sensing enable robots to be used in complex manufacturing tasks. These new capabilities are expanding the role of robotics in manufacturing operations and leading to significant

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16 growth in the industrial robotics area. The third technology covered in Volume 3 is augmented and virtual reality. Augmented and virtual reality (AR/VR) technologies are being leveraged by the manufacturing community to improve operations in a wide variety of ways. Traditional applications have included operator

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16 training and design visualization, with more recent applications including interactive design and manufacturing planning, human and robot interactions, ergonomic analysis, information and knowledge capture, and manufacturing simulation. The advent of low-cost solutions in these areas is accepted to

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16 accelerate the rate of adoption of these technologies in the manufacturing and related sectors. Consisting of chapters by leading experts in the world, Manufacturing in the Era of 4th Industrial Revolution provides a reference set for supporting graduate programs in the advanced manufacturing area.

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16 achievements, findings, and ideas in the robotics field, with particular attention to the Italian scenario. Book coverage includes topics that are related to the theory, design, practice, and applications of robots, such as robot design and kinematics, dynamics of robots and multi-body systems, linkages and manipulators,

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16 control of robotic systems, trajectory planning and optimization, innovative robots and applications, industrial robotics, collaborative robotics, medical robotics, assistive robotics, and service robotics. Book contributions include, but are not limited to, revised and substantially extended versions of selected

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